

**SIEMENS**

Operating Instructions

# SITRANS L

Radar Transmitters

SITRANS LR140

Edition

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<https://www.siemens.com>

## SITRANS L

### Radar Transmitters SITRANS LR140

#### Operating Instructions

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## Legal Information

### Warning Notice System

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

 <b>DANGER</b>
---

indicates that death or severe personal injury will result if proper precautions are not taken.
---

 <b>WARNING</b>
--

indicates that death or severe personal injury may result if proper precautions are not taken.
--

 <b>CAUTION</b>
--

indicates that minor personal injury can result if proper precautions are not taken.
--

 <b>NOTICE</b>
---

indicates that property damage can result if proper precautions are not taken.
--

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

### Qualified Personnel

The product/system described in this documentation may be operated only by **personnel qualified** for the specific task in accordance with the relevant documentation, in particular its warning notices and safety instructions. Qualified personnel are those who, based on their training and experience, are capable of identifying risks and avoiding potential hazards when working with these products/systems.

### Proper Use of Siemens Products

Note the following:

 <b>WARNING</b>
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Siemens products may only be used for the applications described in the catalog and in the relevant technical documentation. If products and components from other manufacturers are used, these must be recommended or approved by Siemens. Proper transport, storage, installation, assembly, commissioning, operation and maintenance are required to ensure that the products operate safely and without any problems. The permissible ambient conditions must be complied with. The information in the relevant documentation must be observed.
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### Disclaimer of Liability

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

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# Preface

Editing status: 2020-08-03



# Introduction

## 1.1 Function

This instruction provides all the information you need for mounting, connection and setup as well as important instructions for maintenance, fault rectification, the exchange of parts and the safety of the user. Please read this information before putting the transmitter into operation and keep this manual accessible in the immediate vicinity of the device.

## 1.2 Target group

This operating instructions manual is directed to trained personnel. The contents of this manual must be made available to the qualified personnel and implemented.

## 1.3 Symbols used



**Information, note, tip:** This symbol indicates helpful additional information and tips for successful work.



**Note:** This symbol indicates notes to prevent failures, malfunctions, damage to devices or plants.



**Caution:** Non-observance of the information marked with this symbol may result in personal injury.



**Warning:** Non-observance of the information marked with this symbol may result in serious or fatal personal injury.



**Danger:** Non-observance of the information marked with this symbol results in serious or fatal personal injury.



### Ex applications

This symbol indicates special instructions for Ex applications.



### List

The dot set in front indicates a list with no implied sequence.

1

**Sequence of actions**

Numbers set in front indicate successive steps in a procedure.



**Battery disposal**

This symbol indicates special information about the disposal of batteries and accumulators.

## Safety notes

### 2.1 Authorised personnel

All operations described in this documentation must be carried out only by trained, qualified personnel authorised by the plant operator.

During work on and with the device, the required personal protective equipment must always be worn.

### 2.2 Appropriate use

SITRANS LR140 is a transmitter for continuous level measurement.

You can find detailed information about the area of application in chapter " *Product description*".

Operational reliability is ensured only if the transmitter is properly used according to the specifications in the operating instructions manual as well as possible supplementary instructions.

### 2.3 Warning about incorrect use

Inappropriate or incorrect use of this product can give rise to application-specific hazards, e.g. vessel overfill through incorrect mounting or adjustment. Damage to property and persons or environmental contamination can result. Also, the protective characteristics of the transmitter can be impaired.

### 2.4 General safety instructions

This is a state-of-the-art transmitter complying with all prevailing regulations and directives. The transmitter must only be operated in a technically flawless and reliable condition. The operator is responsible for the trouble-free operation of the transmitter. When measuring aggressive or corrosive media that can cause a dangerous situation if the transmitter malfunctions, the operator has to implement suitable measures to make sure the transmitter is functioning properly.

The safety instructions in this operating instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed by the user.

For safety and warranty reasons, any invasive work on the device beyond that described in the operating instructions manual may be carried out only by personnel

authorised by the manufacturer. Arbitrary conversions or modifications are explicitly forbidden. For safety reasons, only the accessory specified by the manufacturer must be used.

To avoid any danger, the safety approval markings and safety tips on the device must also be observed.

The low transmitting power of the radar transmitter is far below the internationally approved limits. No health impairments are to be expected with intended use. The band range of the transmission frequency can be found in chapter " *Technical data*".

## 2.5 Radar frequencies for worldwide use

Country specific settings for the radar signals are determined via the frequency. The operating mode must be set in the operating menu via the respective adjustment tool at the beginning of the setup (see chapter " *Setup*" resp. " *Menu overview*").

### **WARNING**

Operating the device without selecting the frequency for the appropriate country group constitutes a violation of the regulations of the radio approvals of the respective country.

Further information can be found in the document " *Regulations for radar level measuring transmitters with radio licenses*" on our homepage.

## 2.6 Installation and operation in the USA and Canada

This information is only valid for USA and Canada. Hence the following text is only available in the English language.

Installations in the US shall comply with the relevant requirements of the National Electrical Code (ANSI/NFPA 70).

Installations in Canada shall comply with the relevant requirements of the Canadian Electrical Code

A Class 2 power supply unit has to be used for the installation in the USA and Canada.

## 2.7 Security information

Siemens provides products and solutions with industrial security functions that support the secure operation of plants, systems, machines and networks.

To protect plants, systems, machines and networks against cyber threats, it is necessary to implement (and continuously maintain) a holistic, state-of-the-art industrial security concept. Siemens products and solutions constitute one element of such a concept.

Customers are responsible for preventing unauthorized access to their plants, systems, machines and networks. Such systems, machines and components should only be connected to an enterprise network or the internet if and to the extent such a connection is necessary and only when appropriate security measures (e.g. firewalls and/or network segmentation) are in place.

For additional information on industrial security measures that may be implemented, please visit <https://www.siemens.com/industrialsecurity>

Siemens products and solutions undergo continuous development to make them more secure. Siemens strongly recommends that product updates are applied as soon as they are available and that the latest product versions are used. Use of product versions that are no longer supported, and failure to apply the latest updates may increase customer's exposure to cyber threats.

To stay informed about product updates, subscribe to the Siemens Industrial Security RSS Feed under: <https://www.siemens.com/industrialsecurity>



## Description

### 3.1 Configuration

#### Scope of delivery

The scope of delivery encompasses:

- SITRANS LR140 radar transmitter
- Information sheet "*Documents and software*" with:
  - Transmitter serial number
  - QR code with link for direct scanning
- Information sheet "*Device Bluetooth and Parameter Access Codes*" with:
  - Bluetooth PIN
  - Bluetooth PUK
  - Device Access PUK

---

#### Note

Optional transmitter features are also described in this operating instructions manual. The respective scope of delivery results from the order specification.

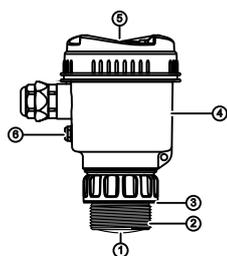
---

#### Scope of this operating instructions

This operating instructions manual applies to the following transmitter versions:

- Hardware version from 1.0.0
- Software version from 1.2.0

#### Constituent parts



- ① Radar antenna
- ② Process fitting

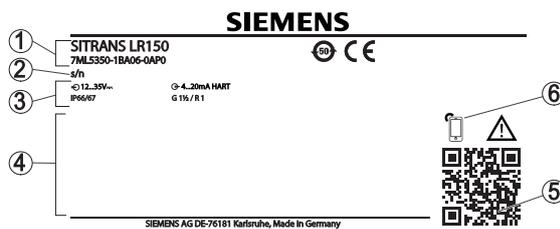
### 3.2 Principle of operation

- ③ Process seal (G type threaded connections only)
- ④ Electronics housing
- ⑤ Housing lid
- ⑥ Ventilation/pressure compensation

Figure 3.1 Components of SITRANS LR140 (Example process fitting G1½)

### Nameplate

The nameplate contains the most important data for identification and use of the transmitter.



- ① Transmitter type
- ② Serial number
- ③ Technical data
- ④ Field for approvals
- ⑤ QR code for device documentation
- ⑥ Wireless access via smart device

Figure 3.2 Layout of the nameplate (example)

## 3.2 Principle of operation

### Application area

SITRANS LR140 is a radar transmitter for non-contact, continuous level measurement. It is suitable for liquids and solids in practically all industries.

### Functional principle

The transmitter emits a continuous, frequency-modulated radar signal through its antenna. The emitted signal is reflected by the medium and received by the antenna as an echo with modified frequency. The frequency change is proportional to the distance and is converted into the level.

## 3.3 Adjustment

### Wireless adjustment

Devices with integrated Bluetooth module can be adjusted wirelessly via Siemens mobile IQ app.

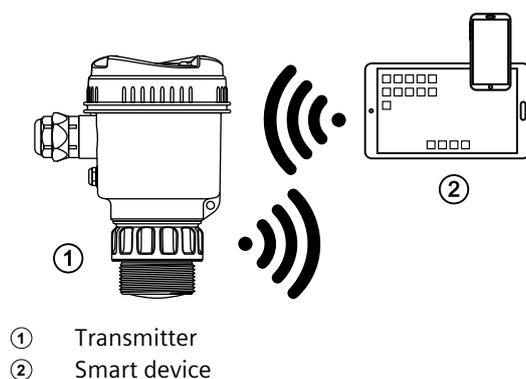


Figure 3.3 Wireless connection to standard operating devices with integrated Bluetooth LE

## 3.4 Packaging, transport and storage

### Packaging

Your transmitter was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a test based on ISO 4180.

The packaging consists of environment-friendly, recyclable cardboard. For special versions, PE foam or PE foil is also used. Dispose of the packaging material via specialised recycling companies.

### Transport

Transport must be carried out in due consideration of the notes on the transport packaging. Nonobservance of these instructions can cause damage to the device.

### Transport inspection

The delivery must be checked for completeness and possible transit damage immediately at receipt. Ascertained transit damage or concealed defects must be appropriately dealt with.

### Storage

Up to the time of installation, the packages must be left closed and stored according to the orientation and storage markings on the outside.

Unless otherwise indicated, the packages must be stored only under the following conditions:

- Not in the open
- Dry and dust free
- Not exposed to corrosive media
- Protected against solar radiation
- Avoiding mechanical shock and vibration

### Storage and transport temperature

- Storage and transport temperature see chapter " *Supplement - Technical data - Ambient conditions* "
- Relative humidity 20 ... 85 %

## Installing/mounting

### 4.1 General instructions

#### Ambient conditions

The transmitter is suitable for standard and extended ambient conditions acc. to DIN/EN/IEC/ANSI/ISA/UL/CSA 61010-1. It can be used indoors as well as outdoors.

#### Process conditions

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**Note**

For safety reasons, the transmitter must only be operated within the permissible process conditions. You can find detailed information on the process conditions in chapter " *Technical data* of the operating instructions or on the nameplate.

---

Hence make sure before mounting that all parts of the transmitter exposed to the process are suitable for the existing process conditions.

These are mainly:

- Active measuring component
- Process fitting
- Process seal

Process conditions in particular are:

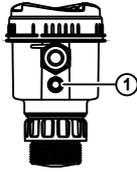
- Process pressure
- Process temperature
- Chemical properties of the medium
- Abrasion and mechanical influences

### 4.2 Mounting instructions

#### Polarisation

Radar transmitters for level measurement emit electromagnetic waves. The polarization is the direction of the electrical component of these waves.

The polarization direction is marked on the housing, see following drawing:



① Marking of the polarisation

Figure 4.1 Position of the polarisation

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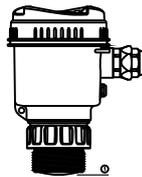
**Note**

When the housing is rotated, the direction of polarization changes and hence the influence of the false echo on the measured value. Please keep this in mind when mounting or making changes later.

---

**Reference point**

The centre of the antenna lens is the beginning of the measuring range and at the same time the reference point for the min./max. adjustment, see following diagram:



① Reference point

Figure 4.2 Reference point

---

**Installation position**

When mounting the device, keep a distance of at least 200 mm (7.874 in) from the vessel wall. If the device is installed in the center of dished or round vessel tops, multiple echoes can arise. However, these can be suppressed by an appropriate adjustment (see chapter "Set up)."

If you cannot maintain this distance, you should carry out a auto false echo suppression during setup. This applies particularly if buildup on the vessel wall is expected. In such cases, we recommend repeating the auto false echo suppression at a later date with existing buildup.

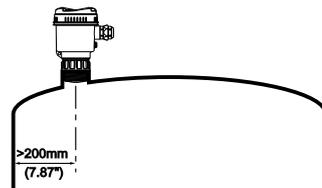


Figure 4.3 Mounting of the radar transmitter on round vessel tops

In vessels with conical bottom it can be advantageous to mount the device in the centre of the vessel, as measurement is then possible down to the bottom.

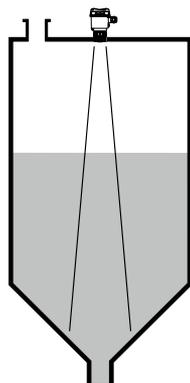


Figure 4.4 Mounting of the radar transmitter on vessels with conical bottom

### Inflowing medium

Do not mount the transmitters in or above the filling stream. Make sure that you detect the medium surface, not the inflowing product.

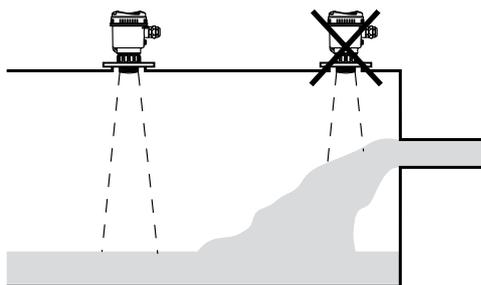


Figure 4.5 Mounting of the radar transmitter with inflowing medium

### Threaded nozzle und nozzle piece

With threaded connection, the antenna end should protrude at least 5 mm (0.2 in) out of the nozzle.

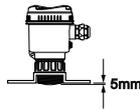


Figure 4.6 Thread mounting

If the reflective properties of the medium are good, you can mount SITRANS LR140 on nozzles longer than the antenna. The nozzle end should be smooth and burr-free, if possible also rounded.

You will find recommended values for nozzle heights in the following illustration or the table. The values come from typical applications. Deviating from the proposed dimensions, also longer nozzles are possible, however the local conditions must be taken into account.

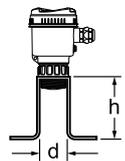


Figure 4.7 Nozzle mounting

Nozzle diameter d		Nozzle length h	
40 mm	1 1/2"	≤ 150 mm	≤ 5.9 in
50 mm	2"	≤ 200 mm	≤ 7.9 in
80 mm	3"	≤ 300 mm	≤ 11.8 in
100 mm	4"	≤ 400 mm	≤ 15.8 in
150 mm	6"	≤ 600 mm	≤ 23.6 in

**Note**

When mounting on longer nozzles, we recommend carrying out a auto false echo suppression (see chapter "Parameter adjustment").

**Orientation**

In liquids, direct the device as perpendicular as possible to the medium surface to achieve optimum measurement results.

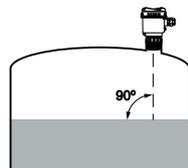


Figure 4.8 Alignment in liquids

## Agitators

If there are agitators in the vessel, a auto false echo suppression should be carried out with the agitators in motion. This ensures that the interfering reflections from the agitators are saved with the blades in different positions.

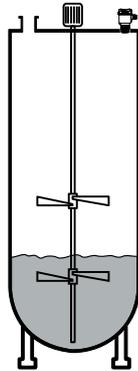


Figure 4.9 Agitators

## Foam generation

Through the action of filling, stirring and other processes in the vessel, compact foams which considerably damp the emitted signals may form on the medium surface.

If foams lead to measurement errors, you should use the biggest possible radar antennas or transmitters with guided radar.

## 4.3 Measurement setup - Flow

In general, the following must be observed while mounting the device:

- Mounting the transmitter on the upstream or inlet side
- Installation in the centre of the flume and vertical to the liquid surface
- Distance to the overfall orifice or Venturi flume
- Min. distance to the max. height of damming for optimum accuracy: 250 mm (9.843 in)<sup>1</sup>

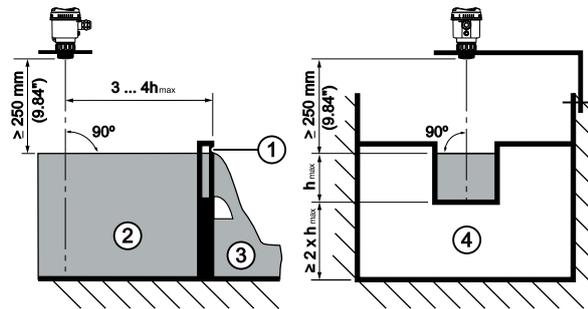
Detailed project planning data can be found at the channel manufacturers and in the technical literature.

The following examples serve as an overview for flow measurement.

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<sup>1</sup> At smaller distances the measuring accuracy is reduced, see "Technical data".

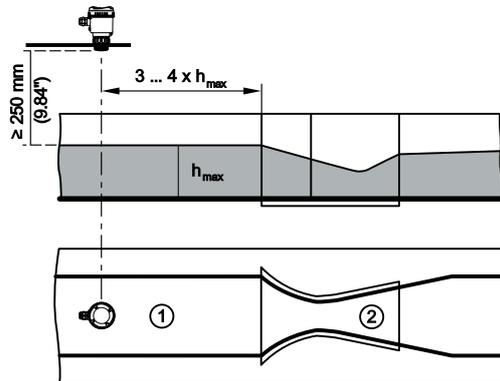
Rectangular overflow



- ① Overfall orifice (side view)
- ② Upstream water
- ③ Tailwater
- ④ Overfall orifice (view from tailwater)

Figure 4.10 Flow measurement with rectangular flume:  $h_{max}$  = max. filling of the rectangular flume

Khafagi-Venturi flume



- ① Position transmitter
- ② Venturi flume

Figure 4.11 Flow measurement with Khafagi-Venturi flume:  $h_{max}$  = max. filling of the flume; B = tightest constriction in the flume

## Connecting

### 5.1 Preparing the connection

#### Safety instructions

Always keep in mind the following safety instructions:

- Carry out electrical connection by trained, qualified personnel authorised by the plant operator

 <b>WARNING</b>
--

Only connect or disconnect in de-energized state.
---

#### Voltage supply

The data for power supply are specified in chapter " *Technical data* .

---

**Note**

Power the transmitter via an energy-limited circuit (power max. 100 W) acc. to IEC 61010-1, e.g.

- Class 2 power supply unit (acc. to UL1310)
- SELV power supply unit (safety extra-low voltage) with suitable internal or external limitation of the output current

Keep in mind the following additional factors that influence the operating voltage:

- Lower output voltage of the power supply unit under nominal load (e.g. with a transmitter current of 20.5 mA or 22 mA in case of fault)
- Influence of additional transmitters in the circuit (see load values in chapter " *Technical data* )

#### Connection cable

Use cable with round cross section for transmitters with housing and cable gland. To ensure the seal effect of the cable gland (IP protection rating), find out which cable outer diameter the cable gland is suitable for.

Shielded, two-wire cable is recommended for connecting the device.

---

**Note**

If the temperatures are too high, the cable insulation can be damaged. Hence keep apart from the ambient temperature also the self-heating of the transmitter for the

temperature resistance of the cable in the connection compartment in mind (With an ambient temperature  $\geq 50\text{ °C}$  (122 °F) the connection cable should be suitable for a temperature which is at least  $20\text{ °C}$  (36 °F) higher.).

---

### Cable screening and grounding

It is recommended to connect the cable screening to ground potential on the supply side.

### Cable gland

#### Metric threads

In the case of transmitter housings with metric thread, the cable gland is screwed in at the factory. It is sealed with plastic plugs as transport protection.

You have to remove this plug before electrical connection.

#### NPT thread

In the case of transmitter housings with self-sealing NPT threads, it is not possible to have the cable entry screwed in at the factory. The cable gland is therefore covered with a red dust protection cap as transport protection.

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#### Note

To ensure the housing protection class, you must replace this protective cap with an approved NPT cable gland before setup.

---

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#### Note

Do not use grease when screwing in the NPT cable gland or a conduit steel pipe.

---

Maximum torque see chapter "*Technical data*".

## 5.2 Connecting

### Connection technology

The voltage supply and signal output are connected via the spring-loaded terminals in the housing.

---

#### Note

Fixed conductors and flexible conductors with ferrules can be inserted directly into the terminal openings. In the case of flexible conductors for opening the terminals, use a screwdriver (3 mm blade width) to push the actuator lever away from the terminal opening. When released, the terminals are closed again.

---



Figure 5.1 Connection

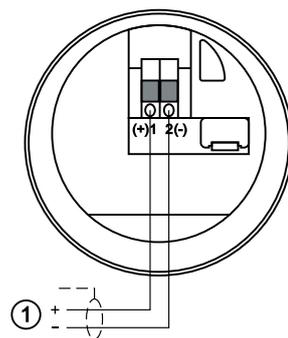
You can find further information on the max. wire cross-section under "*Technical data - Electromechanical data*".

## Connecting

Connect the transmitter according to the following wiring plan.

## 5.3 Wiring plan

### Electronics and connection compartment



① Voltage supply, signal output

Figure 5.2 Connection compartment SITRANS LR140

## 5.4 Switch-on phase

After connection to the power supply, the device carries out a self-test:

- Internal check of the electronics
- Output signal is set to failure

The current measured value is then output on the signal cable.

## Access protection

### 6.1 Bluetooth radio interface

Devices with a Bluetooth radio interface are protected against unwanted access from outside. This means that only authorized persons can receive measured and status values and change device settings via this interface.

#### Bluetooth PIN

A Bluetooth PIN is required to establish Bluetooth communication via the adjustment tool (smartphone/tablet/notebook). This code must be entered once when Bluetooth communication is established for the first time in the adjustment tool. It is then stored in the adjustment tool and does not have to be entered again.

The Bluetooth PIN is individual for each device. It is supplied with the device in the information sheet "*Device Bluetooth and Parameter Access Codes*". It can be changed by the user after the first connection has been established. If the Bluetooth PIN has not been entered correctly, a new entry can only be made after a waiting period has elapsed. The waiting time increases with each additional incorrect entry.

#### Bluetooth PUK

The Bluetooth PUK enables Bluetooth communication to be established in the event that the Bluetooth PIN is no longer known. It can't be changed. The Bluetooth PUK can be found in information sheet "*Device Bluetooth and Parameter Access Codes*". If this document is lost, the Bluetooth PUK can be retrieved from your personal contact person after legitimation. The storage and transmission of Bluetooth access codes is always encrypted (SHA 256 algorithm).

### 6.2 Protection of the parameterization

The settings (parameters) of the device can be protected against unwanted changes. The parameter protection is deactivated on delivery, all settings can be made.

#### user PIN

To protect the parameterization, the device can be locked by the user with the aid of a freely selectable user PIN. The settings (parameters) can then only be read out, but not changed. The user PIN is also stored in the adjustment tool. However, unlike the Bluetooth PIN, it must be re-entered for each unlock. When using the adjustment app or EDD, the stored user PIN is then suggested to the user for unlocking.

### Device Access PUK

The Device Access PUK allows unlocking the device in case the user PIN is no longer known. It can't be changed. The Device Access PUK can also be found on the supplied information sheet " *Device Bluetooth and Parameter Access Codes*. If this document is lost, the Device Access PUK can be retrieved from your personal contact person after legitimation. The storage and transmission of the user PIN is always encrypted (SHA 256 algorithm).

## Setup with smart device (Bluetooth)

### 7.1 Connecting

#### Connecting

Start the adjustment app. The smart device searches automatically for Bluetooth-capable transmitters in the area.

The devices found are listed.

Select the requested transmitter in the device list.

#### Authenticate

When establishing the connection for the first time, the operating tool and the transmitter must authenticate each other. After the first correct authentication, each subsequent connection is made without a new authentication query.

#### Enter Bluetooth access code

For authentication, enter the 6-digit Bluetooth PIN in the next menu window. You can find the code on the information sheet " *Device Bluetooth and Parameter Access Codes* in the device packaging.

---

**Note**

If an incorrect code is entered, the code can only be entered again after a delay time. This time gets longer after each incorrect entry.

---

#### Connected

After connection, the transmitter adjustment menu is displayed on the respective adjustment tool.



## Operating

To configure the device:

1. Download and install the *SITRANS mobile IQ* app from the App store to your mobile device.
2. Launch the app. Devices in range will appear.



3. Click on the device you wish to connect to. On first connection, a PIN code shipped with the device needs to be entered (see *Device Bluetooth and*

Parameter Access Codes sheet). Following successful PIN entry, the device cockpit will be shown.

The screenshot displays the 'Device cockpit' for a SITRANS LR110. At the top, the status bar shows the time 6:15, signal strength, Wi-Fi, and 100% battery. The app header includes 'SITRANS LR110', a 'DISCONNECT' button, and a menu icon. The main content is organized into sections: 'Device cockpit' with a product image and name; 'Serial number', 'FW version', and 'HW version' details; 'Device status' with a green checkmark; and 'Current values' including Level, Distance, Confidence, Loop current, and Percent of range.

Product name	Tag	
SITRANS LR110/120		
Serial number	FW version	HW version
JNB/L8260000091	1.0.1	1.1.0
Device status	✓	
Current values		
Level	Distance	Confidence
12.100 m	2.899 m	43 dB
Loop current	Percent of range	
17.828 mA	86.429 %	

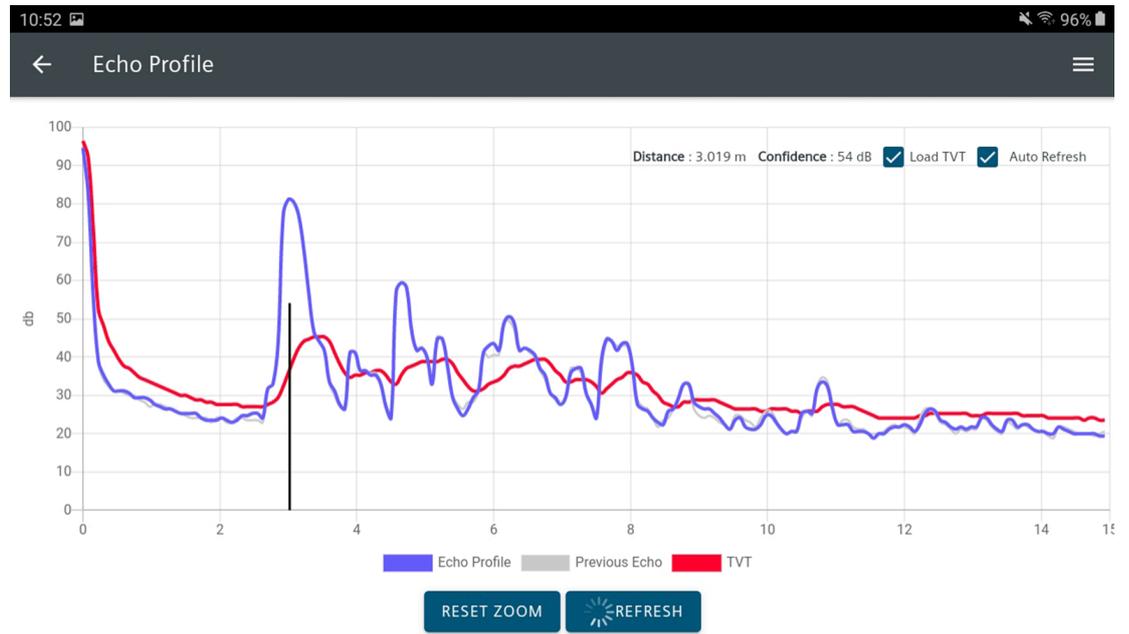
- Use the Setup/Quick Commissioning to configure the transmitter for your application type.

10:47
📶 97% 🔋

← Setup > Quick commissioning
☰

<b>Units</b>	m
<b>Lower calibration point 1</b>	15 m <span style="float: right;">▼</span>
<b>Upper calibration point 2</b>	0 m <span style="float: right;">▼</span>
<b>Operation</b>	Level <span style="float: right;">▼</span>
<b>Material type</b>	Liquids <span style="float: right;">▼</span>
<b>Application</b>	Liquid Process <span style="float: right;">▼</span>

Many diagnostic tools are supported, including the echo profile viewer:



## Diagnostics and troubleshooting

### 9.1 Maintenance

#### Maintenance

If the device is used properly, no special maintenance is required in normal operation.

#### Precaution measures against buildup

In some applications, buildup on the antenna system can influence the measuring result. Depending on the transmitter and application, take measures to avoid heavy soiling of the antenna system. If necessary, clean the antenna system in certain intervals.

#### Cleaning

The cleaning helps that the nameplate and markings on the transmitter are visible.

Take note of the following:

- Use only cleaning agents which do not corrode the housings, nameplate and seals
- Use only cleaning methods corresponding to the housing protection rating

### 9.2 Rectify faults

#### Reaction when malfunction occurs

The operator of the system is responsible for taking suitable measures to rectify faults.

#### Causes of malfunction

The device offers maximum reliability. Nevertheless, faults can occur during operation. These may be caused by the following, e.g.:

- Transmitter
- Process
- Voltage supply

- Signal processing

### Fault rectification

The first measures are:

- Evaluation of fault messages
- Checking the output signal
- Treatment of measurement errors

A smart device (smartphone/tablet) with the adjustment app or a PC/notebook with the PDM and the suitable EDD offer you further comprehensive diagnostic possibilities. In many cases, the causes can be determined in this way and the faults eliminated.

### Reaction after fault rectification

Depending on the reason for the fault and the measures taken, the steps described in chapter " Setup must be carried out again or must be checked for plausibility and completeness.

## 9.3 Diagnosis, fault messages

### 4 ... 20 mA signal

Connect a multimeter in the suitable measuring range according to the wiring plan. The following table describes possible errors in the current signal and helps to eliminate them:

Error	Cause	Rectification
4 ... 20 mA signal not stable	Fluctuating measured value	Set damping
4 ... 20 mA signal missing	Electrical connection faulty	Check connection, correct, if necessary
	Voltage supply missing	Check cables for breaks; repair if necessary
	Operating voltage too low, load resistance too high	Check, adapt if necessary
Current signal greater than 22 mA, less than 3.6 mA	Transmitter electronics defective	Replace device or send in for repair depending on device version

## 9.4 Status messages according to NE 107

The transmitter features self-monitoring and diagnostics according to NE 107 and VDI/VDE 2650. In addition to the status messages in the following tables there are

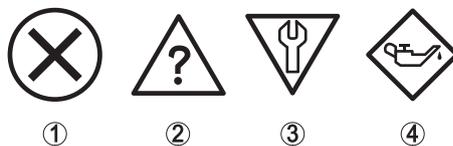
more detailed error messages available under the menu item " *Diagnostics* via the respective adjustment module.

## Status messages

The status messages are divided into the following categories:

- Failure
- Function check
- Out of specification
- Maintenance required

and explained by pictographs:



- ① Failure - red
- ② Out of specification - yellow
- ③ Function check - orange
- ④ Maintenance required - blue

Figure 9.1 Pictographs of the status messages

**Failure:** Due to a malfunction in the transmitter, a fault message is output.

This status message is always active. It cannot be deactivated by the user.

**Function check:** The transmitter is being worked on, the measured value is temporarily invalid (for example during simulation).

This status message is inactive by default.

**Out of specification:** The measured value is unreliable because an transmitter specification was exceeded (e.g. electronics temperature).

This status message is inactive by default.

**Maintenance required:** Due to external influences, the transmitter function is limited. The measurement is affected, but the measured value is still valid. Plan in maintenance for the transmitter because a failure is expected in the near future (e.g. due to buildup).

This status message is inactive by default.

## Failure

Code	Cause	Rectification
F013	No measured value in the switch-on phase or during operation	Check or correct installation and/or parameter settings

Code Text message	Cause	Rectification
no measured value available		Clean the antenna system
F017 Adjustment span too small	Adjustment not within specification	Change adjustment according to the limit values (difference between min. and max. $\geq 10$ mm)
F025 Error in the linearization table	Index markers are not continuously rising, for example illogical value pairs	Check linearization table Delete table/Create new
F036 No operable software	Checksum error if software update failed or aborted	Repeat software update Send transmitter for repair
F040 Error in the electronics	Limit value exceeded in signal processing Hardware error	Restart transmitter Send transmitter for repair
F080 General software error	General software error	Restart transmitter
F105 Determine measured value	The transmitter is still in the start phase, the measured value could not yet be determined	Wait for the end of the switch-on phase Duration up to 3 minutes depending on the measurement environment and parameter settings
F260 Error in the calibration	Checksum error in the calibration values Error in the EEPROM	Send transmitter for repair
F261 Error in the transmitter settings	Error during setup Auto false echo suppression faulty Error when carrying out a reset	Repeat setup Carry out a reset
F265 Measurement function disturbed	Program sequence of the measuring function disturbed	Device restarts automatically

### Function check

Code Text message	Cause	Rectification
C700 Simulation active	A simulation is active	Finish simulation Wait for the automatic end after 60 mins.

## Out of specification

Code Text message	Cause	Rectification
S600 Impermissible electronics temperature	Temperature of the electronics in the non-specified range	Check ambient temperature Insulate electronics
S601 Overfilling	Danger of vessel overfilling	Make sure that there is no further filling Check level in the vessel
S603 Impermissible operating voltage	Terminal voltage too small	Check terminal voltage, increase operating voltage

## Maintenance

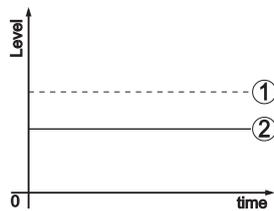
Code Text message	Cause	Rectification
M500 Error in the delivery status	The data could not be restored during the reset to delivery status	Repeat reset Load XML file with transmitter data into the transmitter
M501 Error in the delivery status	Hardware error EEPROM	Send transmitter for repair
M504 Error at a device interface	Hardware defect	Check connections Exchanging the electronics Send transmitter for repair
M505 No echo available	Transmitter does not detect an echo during operation Antenna dirty or defective	Clean the antenna Use a more suitable antenna/transmitter Remove possible false echoes Optimize transmitter position and orientation
M507 Error in the transmitter settings	Error during setup Error when carrying out a reset Auto false echo suppression faulty	Carry out reset and repeat setup
M508 No executable Bluetooth software	Checksum error in Bluetooth software	Carry out software update
M509 Software update running	Software update running	Wait until software update is finished
M510 No communication with the main controller	Communication between main electronics and display module disturbed	Check the connection cable to the display Send transmitter for repair

Code Text message	Cause	Rectification
M511 Inconsistent software configuration	A software unit requires a software update	Carry out software update

## 9.5 Treatment of measurement errors

The tables below give typical examples of application-related measurement errors.

The images in column " *Error description* show the actual level as a dashed line and the output level as a solid line.

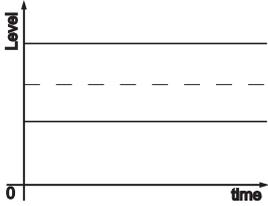
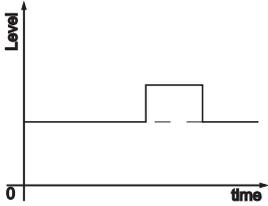


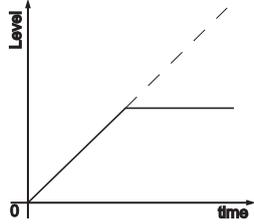
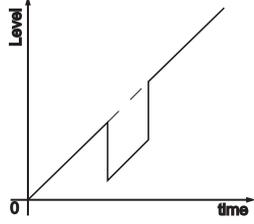
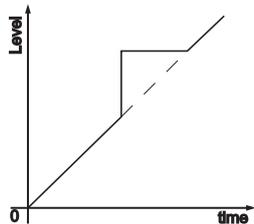
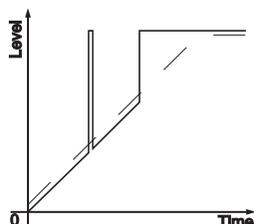
- ① Real level
- ② Level displayed by the transmitter

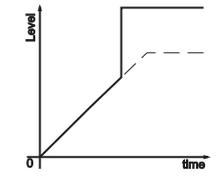
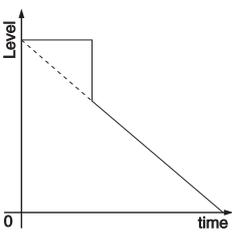
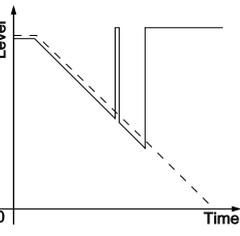
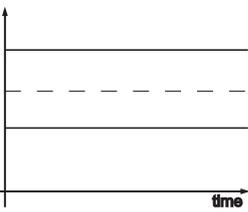
### Note

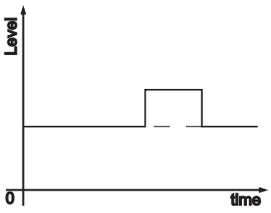
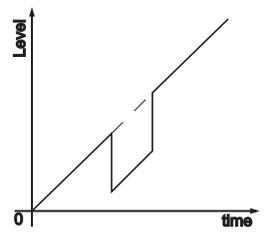
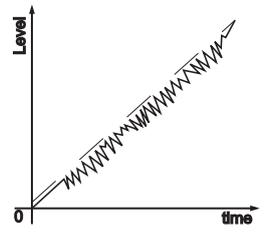
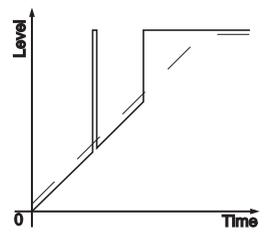
If the output level is constant, the cause could also be the fault setting of the current output to " *Hold value*."

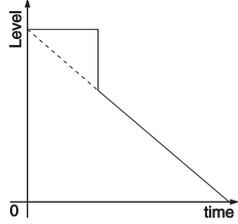
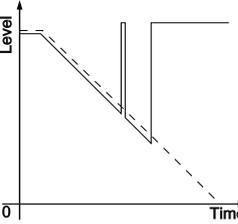
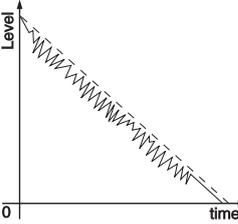
If the level is too low, the reason could be a line resistance that is too high

Fault description	Cause	Rectification
Measured value shows a too low or too high level 	Min./max. adjustment not correct	Adapt min./max. adjustment
	Incorrect linearization curve	Adapt linearization curve
Measured value jumps towards 100 % 	Due to the process, the amplitude of the level echo sinks A auto false echo suppression was not carried out	Carry out a auto false echo suppression
	Amplitude or position of a false signal has changed (e.g. condensation, buildup); auto false echo suppression no longer matches actual conditions	Determine the reason for the changed false signals, carry out auto false echo suppression, e.g. with condensation.

Fault description	Cause	Rectification
<p>Measured value remains unchanged during filling</p> 	<p>False signals in the close range too big or level echo too small Strong foam or vortex generation Max. adjustment not correct</p>	<p>Eliminate false signals in the close range Check measuring point: Antenna should protrude out of the threaded mounting nozzle, possible false echoes through flange nozzle? Remove contamination on the antenna In case of interferences due to installations in the close range, change polarisation direction Create a new auto false echo suppression Adapt max. adjustment</p>
<p>Measured value jumps towards 0 % during filling</p> 	<p>The level echo cannot be distinguished from the false signal at a false signal position (jumps to multiple echo)</p>	<p>In case of interferences due to installations in the close range: Change polarisation direction Chose a more suitable installation position</p>
<p>Measured value jumps towards 100 % during filling</p> 	<p>Due to strong turbulence and foam generation during filling, the amplitude of the level echo sinks. Measured value jumps to false signal</p>	<p>Carry out a auto false echo suppression</p>
<p>Measured value jumps sporadically to 100 % during filling</p> 	<p>Varying condensation or contamination on the antenna</p>	<p>Carry out a auto false echo suppression or increase auto false echo suppression with condensation/contamination in the close range by editing</p>
<p>Measured value jumps to <math>\geq 100\%</math> or 0 m distance</p>	<p>Level echo is no longer detected in the close range due to foam generation or false signals in the close range. The transmitter goes</p>	<p>Check measuring point: Antenna should protrude out of the threaded mounting nozzle, possible false echoes through flange nozzle?</p>

<p><b>Fault description</b></p> 	<p><b>Cause</b></p> <p>into overflow protection mode. The max. level (0 m distance) as well as the status message " <i>Overflow protection</i> " are output.</p>	<p><b>Rectification</b></p> <p>Remove contamination on the antenna</p>
<p><b>Fault description</b></p> <p>Measured value remains unchanged in the close range during emptying</p> 	<p><b>Cause</b></p> <p>False signal larger than the level echo Level echo too small</p>	<p><b>Rectification</b></p> <p>Check measuring point: Antenna should protrude out of the threaded mounting nozzle, possible false echoes through flange nozzle? Remove contamination on the antenna In case of interferences due to installations in the close range: Change polarisation direction After eliminating the false signals, the auto false echo suppression must be deleted. Carry out a new auto false echo suppression</p>
<p><b>Fault description</b></p> <p>Measured value jumps sporadically towards 100 % during emptying</p> 	<p><b>Cause</b></p> <p>Varying condensation or contamination on the antenna</p>	<p><b>Rectification</b></p> <p>Carry out auto false echo suppression or increase auto false echo suppression in the close range by editing</p>
<p><b>Fault description</b></p> <p>Measured value shows a too low or too high level</p> 	<p><b>Cause</b></p> <p>Min./max. adjustment not correct Incorrect linearization curve</p>	<p><b>Rectification</b></p> <p>Adapt min./max. adjustment Adapt linearization curve</p>
<p><b>Fault description</b></p> <p>Measured value jumps towards 100 %</p>	<p><b>Cause</b></p> <p>Due to the process, the amplitude of the product echo decreases A auto false echo suppression was not carried out Amplitude or position of a false signal has changed (e.g. condensation, buildup); auto</p>	<p><b>Rectification</b></p> <p>Carry out a auto false echo suppression Determine the reason for the changed false signals, carry out</p>

Fault description	Cause	Rectification
	false echo suppression no longer matches actual conditions	auto false echo suppression, e.g. with condensation.
<p>Measured value jumps towards 0 % during filling</p> 	<p>The level echo cannot be distinguished from the false signal at a false signal position (jumps to multiple echo)</p> <p>Transverse reflection from an extraction funnel, amplitude of the transverse reflection larger than the level echo</p>	<p>Remove/reduce false signal: minimize interfering installations by changing the polarization direction</p> <p>Chose a more suitable installation position</p> <p>Direct transmitter to the opposite funnel wall, avoid crossing with the filling stream</p>
<p>Measured value fluctuates around 10 ... 20 %</p> 	<p>Various echoes from an uneven medium surface, e.g. a material cone</p> <p>Reflections from the medium surface via the vessel wall (deflection)</p>	<p>Check parameter "Material Type" and adapt, if necessary</p> <p>Optimize installation position and transmitter orientation</p> <p>Select a more suitable installation position, optimize transmitter orientation, e.g. with a swivelling holder</p>
<p>Measured value jumps sporadically to 100 % during filling</p> 	Changing condensation or contamination on the antenna	Carry out a auto false echo suppression or increase auto false echo suppression with condensation/contamination in the close range by editing
<p>Measured value remains unchanged in the close range during emptying</p>	False signal greater than level echo or level echo too small	<p>Eliminate false signals in the close range. Check: Antenna must protrude out of the nozzle</p> <p>Remove contamination on the antenna</p> <p>Minimize interfering installations in the close range by changing the polarization direction</p>

Fault description	Cause	Rectification
		After eliminating the false signals, the auto false echo suppression must be deleted. Carry out a new auto false echo suppression
Measured value jumps sporadically towards 100 % during emptying 	Changing condensation or contamination on the antenna	Carry out auto false echo suppression or increase auto false echo suppression in the close range by editing
Measured value fluctuates around 10 ... 20 % 	Various echoes from an uneven medium surface, e.g. an extraction funnel  Reflections from the medium surface via the vessel wall (deflection)	Check parameter "Material Type" and adapt, if necessary  Optimize installation position and transmitter orientation

## 9.6 Return procedure

Enclose the delivery note, the return goods delivery note and the decontamination declaration in a clear plastic pouch and attach it firmly to the outside of the packaging. Any devices/replacement parts which are returned without a decontamination declaration will be cleaned at your expense before further processing.

### Required forms:

- Delivery note
- Return goods delivery note with the following information: <https://www.siemens.com/processinstrumentation/returngoodsnote>
  - Product (item description)
  - Number of returned devices/replacements parts
  - Reason for returning the item(s)

- Decontamination declaration
  - <https://www.siemens.com/sc/declarationofdecontamination>

With this declaration you warrant that the device/replacement part has been carefully cleaned and is free of residues. The device/replacement part does not pose a hazard for humans and the environment.

If the returned device/replacement part has come into contact with poisonous, corrosive, flammable or water-contaminating substances, you must thoroughly clean and decontaminate the device/replacement part before returning it in order to ensure that all hollow areas are free from hazardous substances. Check the item after it has been cleaned.

Any devices/replacement parts returned without a decontamination declaration will be cleaned at your expense before further processing.

## 9.7 Technical support

### Technical Support

If this documentation does not provide complete answers to any technical questions you may have, contact technical support at <http://www.siemens.com/automation/support-request>.

More information about our technical support is available at <http://www.siemens.com/automation/csi/service>

### Internet service and support

In addition to our documentation, Siemens provides a comprehensive support solution at <http://www.siemens.com/automation/service&support>

### Contact person

If you have additional questions about the device, please contact your Siemens personal contact at <http://www.automation.siemens.com/partner>

To find the personal contact for your product, go to " *All products and Branches* and select " *Products and services > Industrial automation > Process transmitter*."

### Documentation

Documentation on the various products and systems can be found at <http://www.siemens.com/processinstrumentation/documentation>.

## **Certificates**

You can find certificates in the Internet under <http://www.siemens.com/processinstrumentation/certificates> or on an included DVD.

## **9.8 How to proceed if a repair is necessary**

If it is necessary to repair the transmitter, please contact Siemens. You find the locations on "[www.siemens.com/processautomation](http://www.siemens.com/processautomation) [<https://www.siemens.com/processautomation>].

## Service and maintenance

### 10.1 Dismounting steps

 **WARNING**

Before dismounting, be aware of dangerous process conditions such as e.g. pressure in the vessel or pipeline, high temperatures, corrosive or toxic media etc.

Take note of chapters " *Mounting* and " *Connecting to voltage supply* and carry out the listed steps in reverse order.

### 10.2 Disposal

The device is made of recyclable materials. For this reason, it should be disposed of by a specialist recycling company. Observe the applicable national regulations.

Devices described in this manual should be recycled. They may not be disposed of in the municipal waste disposal services according to the Directive 2012/19/EC on waste electronic and electrical equipment (WEEE).

Devices can be returned to the supplier within the EC, or to a locally approved disposal service for eco-friendly recycling. Observe the specific regulations valid in your country.

Further information about devices containing batteries can be found at: ( <https://support.industry.siemens.com/cs/document/109479891/>)

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**Note**

**Special disposal required**

The device includes components that require special disposal.

- Dispose of the device properly and environmentally through a local waste disposal contractor.
-



## Certificates and approvals

### 11.1 Radio licenses

#### **Radar**

The device has been tested and approved in accordance with the current edition of the applicable country-specific norms or standards.

Regulations for use can be found in the document "*Regulations for radar level measuring transmitters with radio licenses*" on our homepage.

#### **Bluetooth**

The Bluetooth radio module in the device has been tested and approved according to the current edition of the applicable country-specific norms or standards.

The confirmations as well as regulations for use can be found in the document "*Radio licenses*" supplied or on our homepage.

### 11.2 EU conformity

The device fulfils the legal requirements of the applicable EU directives. By affixing the CE marking, we confirm the conformity of the transmitter with these directives.

The EU conformity declaration can be found on our homepage.



## Technical data and dimensions

### 12.1 Technical data

#### Note for approved transmitters

##### Device specifications:

Siemens makes every effort to ensure the accuracy of these specifications, but reserves the right to change them at any time.

##### Device-specific approvals:

The device-specific approvals are always to be found on the type plates on the device.

#### Materials and weights

<b>Materials, wetted parts</b>	
Antenna, process fitting	PVDF
Process seal	FKM
<b>Materials, non-wetted parts</b>	
Housing	Plastic PBT (Polyester)
Housing seals	O-rings (silicone)
Cable gland	PA
Sealing, cable gland	NBR
Blind plug, cable gland	PA
<b>Weight</b>	0.7 kg (1.543 lbs)

#### Torques

<b>Max. torque mounting boss</b>	7 Nm (5.163 lbf ft)
<b>Max. torque for NPT cable glands and Conduit tubes</b>	10 Nm (7.376 lbf ft)

#### Input variable

<b>Measured variable</b>	The measured variable is the distance between the antenna edge of the transmitter and the medium surface. The antenna edge is also the reference point for the measurement.
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12.1 Technical data

<b>Max. measuring range<sup>a</sup></b>	8 m (26.25 ft)
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<sup>a</sup> Depending on application and medium

Switch-on phase

<b>Start-up time with operating voltage <math>U_B</math></b>	< 15 s
<b>Starting current (for run-up time)</b>	$\leq 3.6$ mA

Output variable

<b>Output signal</b>	4 ... 20 mA
<b>Range of the output signal</b>	3.8 ... 20.5 mA (default setting)
<b>Signal resolution</b>	0.3 $\mu$ A
<b>Resolution, digital</b>	1 mm (0.039 in)
<b>Fault signal, current output (adjustable)</b>	$\leq 3.6$ mA, $\geq 21$ mA, last valid measured value
<b>Max. output current</b>	22 mA
<b>Load</b>	See load resistance under Power supply
<b>Starting current</b> • Load	$\leq 3.6$ mA; $\leq 10$ mA for 5 ms after switching on 600 Ohm at 24 V DC
<b>Damping (63 % of the input variable), adjustable</b>	0 ... 999 s

Deviation (according to DIN EN 60770-1)

<b>Process reference conditions according to DIN EN 61298-1</b>	
Temperature	+18 ... +30 °C (+64 ... +86 °F)
Relative humidity	45 ... 75 %
Air pressure	860 ... 1060 mbar/86 ... 106 kPa (12.5 ... 15.4 psig)
<b>Installation reference conditions</b>	
Distance to installations	> 200 mm (7.874 in)
Reflector	Flat plate reflector
False reflections	Biggest false signal, 20 dB smaller than the useful signal
<b>Deviation with liquids</b>	
Measuring distance > 0.25 m/0.8202 ft	$\leq 5$ mm
Measuring distance $\leq 0.25$ m/0.8202 ft	$\leq 10$ mm
<b>Non-repeatability<sup>a</sup></b>	$\leq 5$ mm
<b>Deviation with bulk solids</b>	The values depend to a great extent on the application. Binding specifications are thus not possible.

<sup>a</sup> Already included in the meas. deviation

### Variables influencing measurement accuracy

Temperature drift - Digital output	< 3 mm/10 K, max. 5 mm
Temperature drift - Current output	< 0.03 %/10 K or max. 0.3 % relating to the 16.7 mA span
Deviation in the current output due to digital/analogue conversion	< 15 µA
<b>Additional deviation through electromagnetic interference</b>	
According to NAMUR NE 21	< 80 µA
According to EN 61326-1	None
According to IACS E10 (shipbuilding)/IEC 60945	< 250 µA

### Characteristics and performance data

Measuring frequency	W-band (80 GHz technology)
Measuring cycle time <sup>a</sup>	≤ 250 ms
Step response time <sup>b</sup>	≤ 3 s
Beam angle <sup>c</sup>	8°

<sup>a</sup> With operating voltage  $U_B \geq 24$  V DC

<sup>b</sup> Time span after a sudden distance change from 1 m to 5 m until the output signal reaches 90 % of the final value for the first time (IEC 61298-2). Valid with operating voltage  $U_B \geq 24$  V DC.

<sup>c</sup> Outside the specified beam angle, the energy level of the radar signal is 50% (-3 dB) less.

### Ambient conditions

Ambient temperature	-40 ... +60 °C (-40 ... +140 °F)
Storage and transport temperature	-40 ... +80 °C (-40 ... +176 °F)

### Mechanical environmental conditions

Vibrations (sinusoidal vibrations)	Class 4M8 (5 g at 4 ... 200 Hz acc. to IEC 60271-3-4)
Impacts (mechanical shock)	Class 6M4 (50 g, 2.3 ms acc. to IEC 60271-3-6)
Impact resistance	IK07 acc. to IEC 62262

### Process conditions

Process temperature	-40 ... +60 °C (-40 ... +140 °F)
Process pressure	-1 ... 3 bar (-100 ... 200 kPa/-14.5 ... 43.51 psig)

### Electromechanical data

Cable entry
-------------

12.1 Technical data

Options	M20 x 1.5; ½ NPT
Cable gland	M20 x 1.5 (cable diameter 5 ... 9 mm)
Closing cap	½ NPT
<b>Wire cross-section (spring-loaded terminals)</b>	
Stranded wire	0.2 mm <sup>2</sup> (AWG 24) ... 2.5 mm <sup>2</sup> (AWG 14)

**Bluetooth interface**

<b>Bluetooth standard</b>	Bluetooth 5.0 (downward compatible to Bluetooth 4.0 LE)
<b>Frequency</b>	2.402 ... 2.480 GHz
<b>Max. emitted power</b>	+2.2 dBm
<b>Max. number of participants</b>	1
<b>Effective range typ. <sup>a</sup></b>	25 m (82 ft)

<sup>a</sup> Depending on the local conditions

**Adjustment**

<b>Smart device</b>	SITRANS mobile IQ
---------------------	-------------------

**Voltage supply**

<b>Operating voltage U<sub>B</sub></b>	
at 4 mA	12 ... 35 V DC
at 20 mA	9 ... 35 V DC
<b>Reverse voltage protection</b>	Integrated

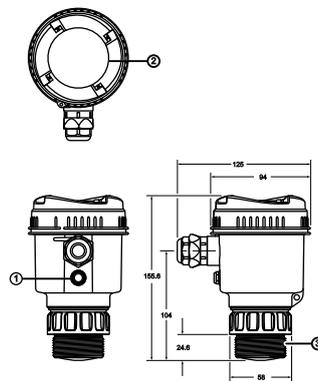
**Overvoltage protection**

<b>Dielectric strength against metallic mounting parts</b>	> 10 kV
<b>Overvoltage resistance (test impulse voltages 1.2/50 µs at 42 Ω)</b>	> 1000 V
<b>Additional overvoltage arrester</b>	Due to the floating structure of the electronics and comprehensive insulation measures generally not necessary.

**Electrical protective measures**

<b>Protection rating</b>	IP66/IP67 acc. to IEC 60529 Type 4X acc. to UL 50
<b>Altitude above sea level</b>	5000 m (16404 ft)
<b>Protection class</b>	III
<b>Pollution degree</b>	4

## 12.2 Dimensions



- ① Ventilation/pressure compensation
- ② Housing lid
- ③ Process fitting

Figure 12.1 Dimensions SITRANS LR140

## 12.3 Licensing information for open source software

Open source software components are also used in this device. A documentation of these components with the respective license type, the associated license texts, copyright notes and disclaimers can be found on our homepage.

## 12.4 Trademark

All the brands as well as trade and company names used are property of their lawful proprietor/originator.

12.4 Trademark

## Further Information

Process Automation

<https://www.siemens.com/processautomation>

Industry Online Support (service and support)

<https://support.industry.siemens.com>

Industry Mall

<https://mall.industry.siemens.com>

Siemens AG

Digital Industry

Process Automation

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